



CERAMIC SENSORS BEHAVIOR

Contents

This short paper is to describe typical behaviour of City Sensors Ceramic Pressure Sensors based on the Thick Film Strain Gage Technology.

It is dealing with:

- ▣ **Temperature behaviour:**
 - Thermal Zero Drift
 - Thermal Sensitivity Shift
- ▣ **Time Influence** (Long Term Stability)
- ▣ **Mechanical Fatigue** (Life Time)

I) Temperature behaviour

As every physical measuring instrument, our Ceramic Pressure Sensors are temperature sensitive.

As a first approach, let us see what happens on any kind of instrument:

Temperature variations affect both:

- ▣ The Zero point (offset) at null pressure
- ▣ The sensitivity of the instrument

Please refer to drawing 1:

This drawing shows the calibration curve of the instrument at 3 different temperatures T1, T2 & T3

T1 supposed to be the room temperature (for example 20 °C) generates a Zero point Z1. Then when the Pressure increases from Zero to the FS (Full Scale), the curve S1 appears which exhibits the proportionality α_1 between the pressure applied and the output signal (mV for instance).

It is supposed that the response is linear, as shown.

When the Temperature increases from T1 to T2 (for example 100 °C), the Zero point moves from Z1 to Z2 and the response curve exhibits a new sensitivity coefficient α_2 different of α_1



When the Temperature decreases from T1 to T3 (for example - 40 °C), the Zero point moves from Z1 to Z3 and the response curve exhibits a new sensitivity coefficient α_3 different of α_1 .

The displacement of the Zero point from Z1 to Z2 or Z3 is called the **Thermal Zero Drift**. It is expressed in % of the FSO / °C (FSO = Full Scale Output).

The change of the angle α from α_1 to α_2 or α_3 is called the **Thermal Sensitivity Shift**. It is expressed in % / °C.

Consequently, it is usually necessary to compensate both the Zero Drift and the Sensitivity Shift.

In the case of our **Ceramic Pressure Sensors**, the selection of materials used and their Heat Treatment (at very High Temperatures, up to about 900 °C), makes so that the **Thermal Sensitivity Shift is self compensated**.

In other words, the curves S2 and S3 are parallel to S1.

In practise, it means that the sensitivity variation is $< 0.01\% / ^\circ\text{C}$.

Consequently, it is only necessary to compensate the Zero Drift. This simplifies considerably the experiments (No need to submit the sensors to temperature and pressure variations simultaneously).

In order to facilitate the Zero Drift compensation, our **Ceramic Sensors are equipped with a Thermistor**, screen printed directly onto the ceramic diaphragm so that it takes the fluid temperature quite immediately (because Ceramic is a very good conductive material for Heat).

To know more about the thermal compensation method, please refer to the **Technical Note # TN 04** based on the use of a screen printed Thermistor (NTC).

Whatever be the compensated type of sensor, this compensation generates a very little residual effect of temperature $< +/- 1\% \text{ FSO} / 100\text{ }^\circ\text{C}$ (including Zero + Span).

▫ Long Term Stability (Time influence)

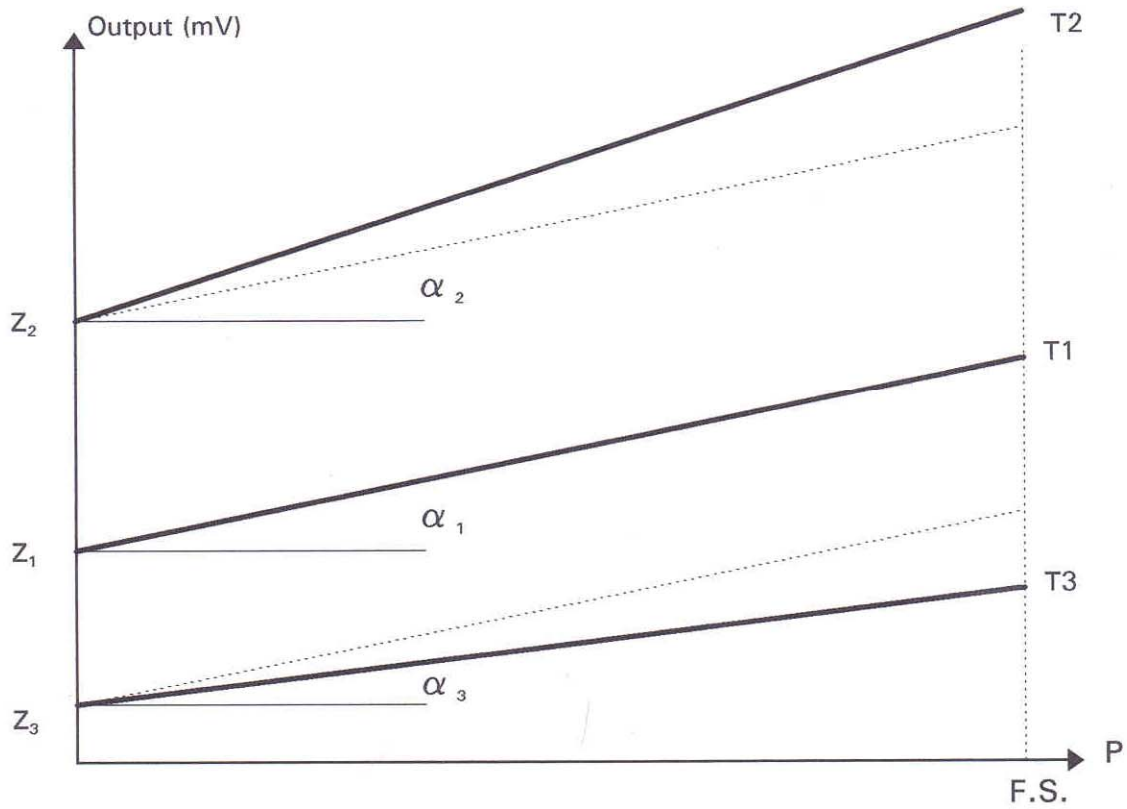
Even at null Pressure and constant Temperature, any kind of instrument exhibits a change of Zero point versus time.

This is generally due to long term changes of materials characteristics which generate changes of internal stresses resulting in changes of strain and consequently changes of apparent Zero.

For most of usual sensors and transducers, the change of Zero point versus time is generally cumulative. This is particularly important when it is not possible to release the Pressure on the Process from time to time in order to measure the drift of the Zero point.

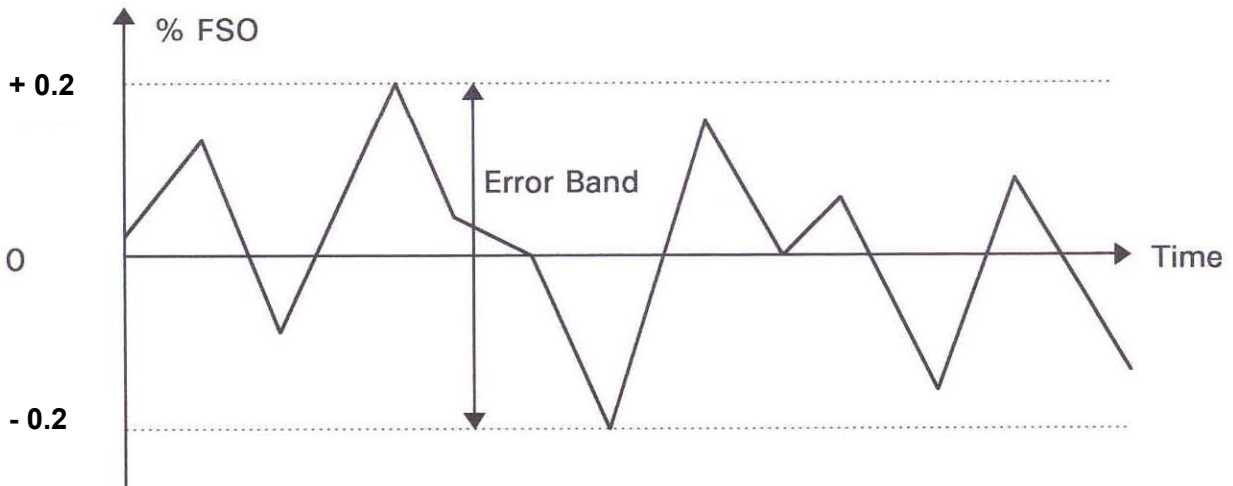
In the case of our **Ceramic Pressure Sensors**, the Zero point versus time is a random value which always remain within a given "error band" See drawing 2.

This error band is typically $< \pm 0.2\% \text{ FS}$



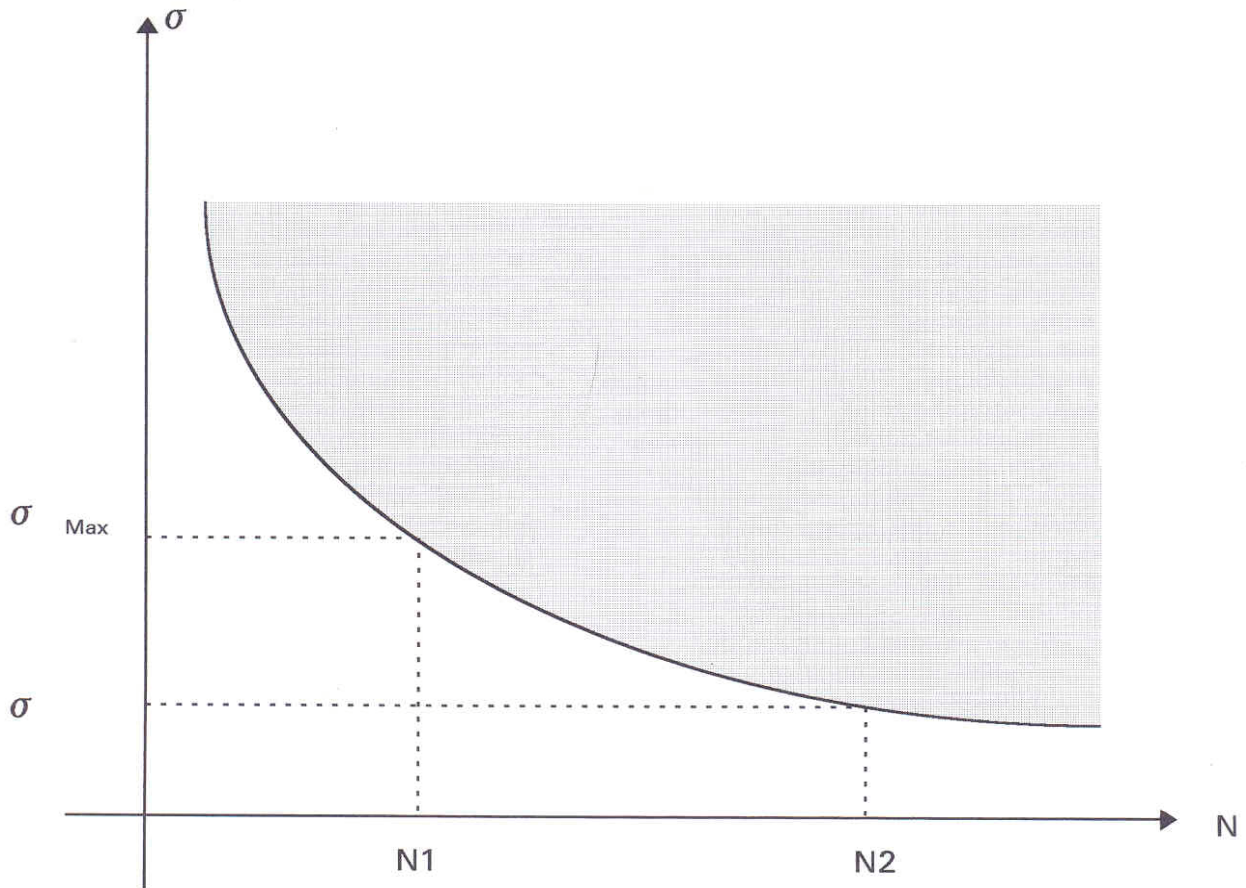
Drawing 1

Temperature Influence



Drawing 2

Long term Stability



Drawing 3

Number of Cycles before Rupture